

SOFTWARE SAFETY INTEGRITY AND SOFTWARE SYSTEMATIC CAPABILITY IN PROCESS INDUSTRY



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- Professional engineer (P.Eng.)
- Project Management Professional (PMP)
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- 20 Years in Automation



AGENDA

- Overview of Failure Types
- IEC 61508 / IEC 61511 Standards
- Safety Integrity
- Systematic Capability
- Management of Software Safety Integrity
- System Safety Lifecycle
- Software Safety Lifecycle
- Software Systematic Capability
- Management of Functional Safety



Introduction

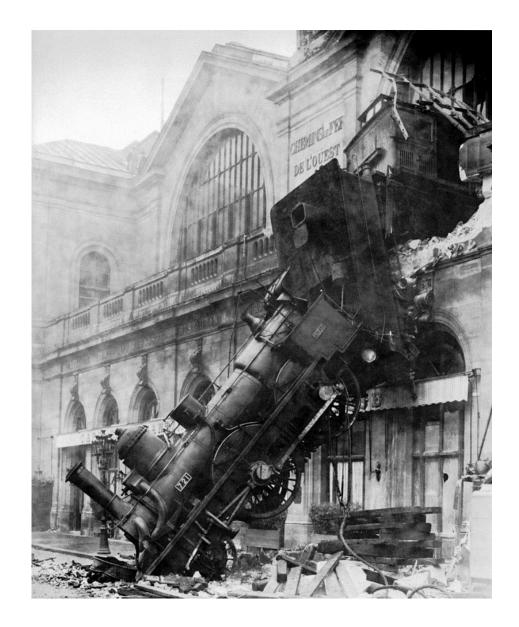
Failure and Overview of Failure Types



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Failure

FAILURE IS THE STATE OR CONDITION OF NOT MEETING A DESIRABLE OR INTENDED FUNCTION





Failure Types

A SYSTEM MAY FAIL TO FUNCTION AS REQUESTED DUE TO:

• RANDOM FAILURE

OR

• SYSTEMATIC FAILURE



Random Failure

- RELATED TO THE HARDWARE COMPONENTS
- DUE TO PHYSICAL CAUSE

ALSO OCCURS DUE TO VARIOUS RANDOM EVENTS SUCH AS:

- ABNORMAL PROCESS CONDITIONS
- CORROSION, THERMAL STRESSING, ...
- WEAR-OUT / TIRE-OUT
- LOW FREQUENCY ATMOSPHERIC EVENT (SNOW IN DESERT)
- NO PATTERN
- IS RANDOM!





Random Failure





Systematic Failure

- DUE TO A DETERMINISTIC WAY TO A ROOT CAUSE
- CAUSED BY HUMAN ERROR DURING:
 - > DESIGN
 - > SPECIFICATION
 - > DEVELOPMENT
 - > MANUFACTURE
 - > INSTALLATION
 - > OPERATION
 - > MAINTENANCE
 - > DECOMMISSIONING



Systematic Failure

- PATTERN
- IMPOSSIBLE TO ANALYZE IN A PROBABILISTIC MANNER
- IS NOT CONSIDERED IN THE VERIFICATION CALCULATION (NOT PART OF PFD)

CANNOT BE QUANTIFIED



Systematic Failure





Systematic vs. Random



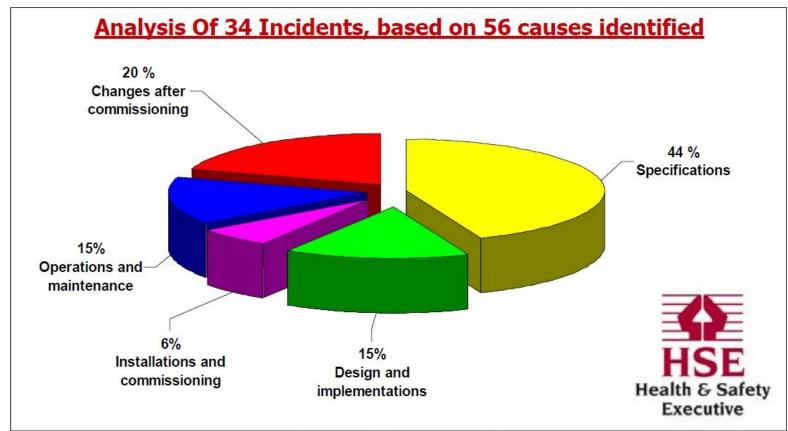
35 MAJOR INCIDENTS BETWEEN 1987 AND 2012

ANGEL CASAL. 2011, 'SIS PITFALLS, MAJOR ACCIDENTS AND LESSONS LEARNED'



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Systematic vs. Random

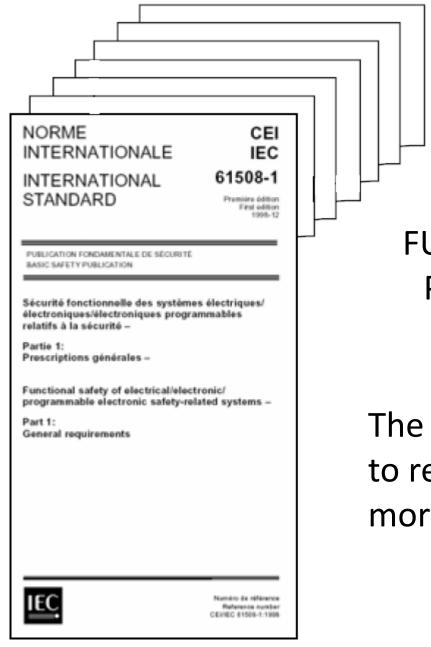


Out of control

Why control systems go wrong and how to prevent failure?

(2nd edition, source: © Health & Safety Executive HSE – UK)





INTERNATIONAL ELECTROTECHNICAL COMMISSION (IEC)

FUNCTIONAL SAFETY OF ELECTRICAL/ELECTRONIC/ PROGRAMMABLE ELECTRONIC SAFETY-RELATED SYSTEMS (IEC-61508)

The standards were a natural evolution for the need to reduce process risk and improve safety through a more formalized and quantifiable methodology.

GM

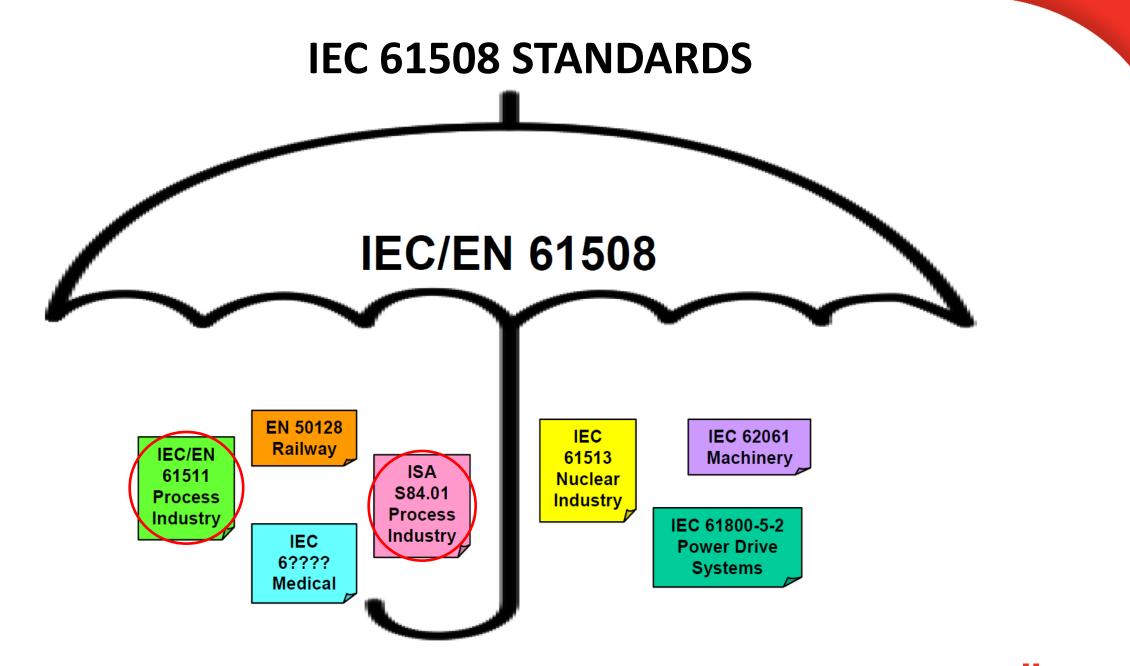


IEC 61508 Standards

SPECIFICALLY FOR IEC 61508, AS THE APPLICATION AND USAGE OF SOFTWARE HAS EVOLVED AND PROLIFERATED, THERE WAS AN INCREASED NEED TO DEVELOP A STANDARD TO GUIDE SYSTEM / PRODUCT DESIGNERS AND DEVELOPERS IN WHAT THEY NEEDED TO DO TO ENSURE AND "CLAIM" THAT THEIR SYSTEMS / PRODUCTS WERE ACCEPTABLY SAFE FOR THEIR INTENDED USES.

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Safety Integrity

ACHIEVEMENT SAFETY INTEGRITY

TARGET RISK REDUCTION

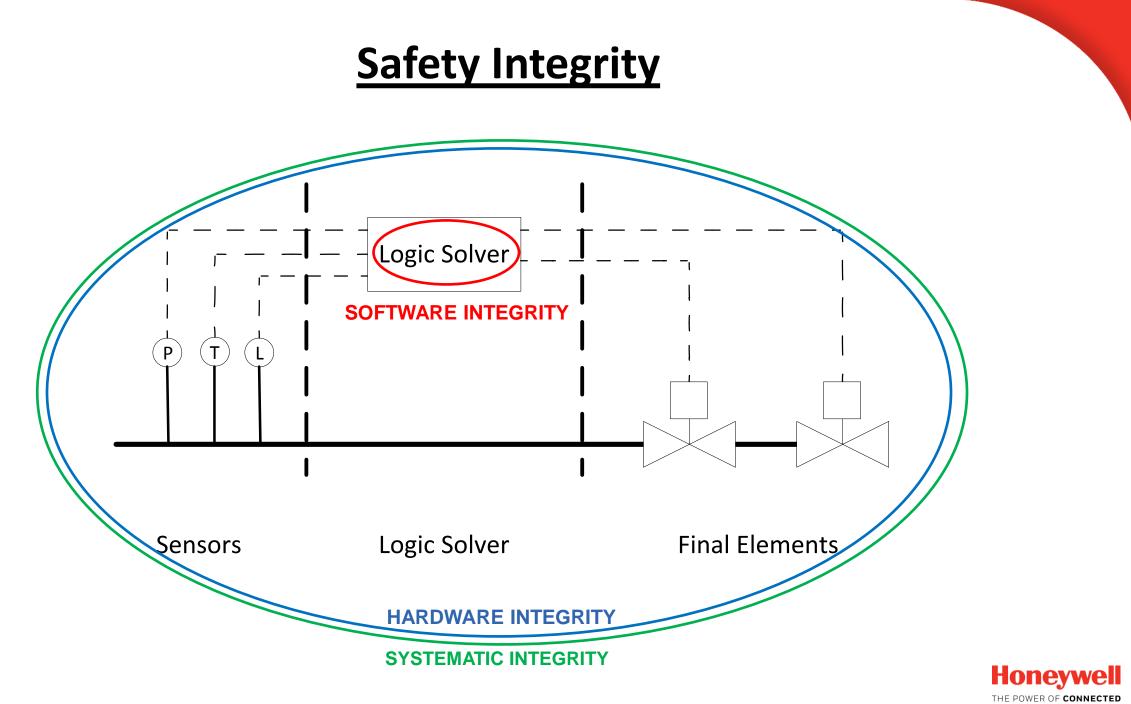
IEC 61511.1—2016: AVERAGE PROBABILITY OF A SAFETY INSTRUMENTED SYSTEM SATISFACTORILY PERFORMING THE REQUIRED SAFETY INSTRUMENTED FUNCTIONS UNDER ALL THE STATED CONDITIONS WITHIN A STATED PERIOD OF TIME

SAFETY INTEGRITY COMPRISES:

<u>HARDWARE SAFETY INTEGRITY</u> (RELATED TO RANDOM FAILURE)

AND

<u>SYSTEMATIC SAFETY INTEGRITY – INCLUDING SOFTWARE SAFETY INTEGRITY-</u> (RELATED TO **SYSTEMATIC FAILURE**)



Systematic Safety Integrity

SYSTEMATIC SAFETY INTEGRITY (AND SOFTWARE SAFETY INTEGRITY) IS TO DO WITH THE MANAGEMENT OF SYSTEMATIC FAILURES:

IEC 61511.1—2016: 3.5.5 SOFTWARE SAFETY INTEGRITY PART OF SAFETY INTEGRITY OF A SAFETY-RELATED SYSTEM RELATING TO SYSTEMATIC FAILURE IN A DANGEROUS MODE OF FAILURE THAT ARE ATTRIBUTABLE TO SOFTWARE

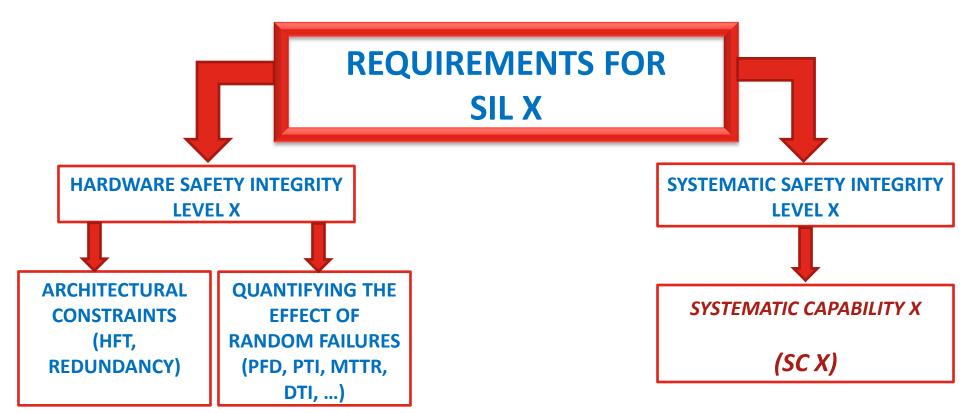
3.5.6 SYSTEMATIC SAFETY INTEGRITY PART OF THE SAFETY INTEGRITY OF A SAFETY-RELATED SYSTEM RELATING TO SYSTEMATIC FAILURES IN A DANGEROUS MODE OF FAILURE



Safety Integrity Level (SIL)

HOW MUCH RISK REDUCTION REQUIRED?

4 LEVEL OF SAFETY INTEGRITY DEFINED BY IEC 61508-2010 : SIL 1 TO SIL 4





Systematic Capability (SC)

- THE SYSTEMATIC SAFETY INTEGRITY OF AN ELEMENT MEETS THE REQUIREMENTS OF THE SPECIFIED SIL
- IS DETERMINED WITH REFERENCE TO THE REQUIREMENTS FOR THE AVOIDANCE AND CONTROL OF SYSTEMATIC FAULTS
- MEASURE ON A SCALE OF SC 1 TO SC 4

SIL X REQUIRES SC X

FOR A SIL N SIF WE NEED SC N SYSTEMATIC CAPABILITY IN OUR ENGINEERING AND IN OUR SOFTWARE.



Achieving Systematic Capability

- ROUTE 1_S: COMPLIANCE WITH THE REQUIREMENTS FOR THE <u>AVOIDANCE</u> OF SYSTEMATIC FAULTS AND THE REQUIREMENTS FOR THE <u>CONTROL</u> OF SYSTEMATIC FAULTS
- ROUTE 2_S: COMPLIANCE WITH THE REQUIREMENTS FOR EVIDENCE THAT THE EQUIPMENT IS PROVEN IN USE
- ROUTE 3_S: COMPLIANCE WITH THE REQUIREMENTS OF IEC 61508.3-2010,
 7.4.2.12 (PRE-EXISTING SOFTWARE ELEMENTS ONLY)



Route 1_s

- 1. AVOIDANCE OF SYSTEMATIC FAULTS (IEC 61508.2-2010 ANNEX B)
 - a) TABLE B.1 TECHNIQUES AND MEASURES TO AVOID MISTAKES DURING SPECIFICATION OF SYSTEM DESIGN REQUIREMENTS
 - b) TABLE B.2 TECHNIQUES AND MEASURES TO AVOID INTRODUCING FAULTS DURING SYSTEM DESIGN AND DEVELOPMENT
 - c) TABLE B.3 TECHNIQUES AND MEASURES TO AVOID FAULTS DURING SYSTEM INTEGRATION
 - d) TABLE B.4 TECHNIQUES AND MEASURES TO AVOID FAULTS AND FAILURES DURING SYSTEM OPERATION AND MAINTENANCE
 - e) TABLE B.5 TECHNIQUES AND MEASURES TO AVOID FAULTS DURING SYSTEM SAFETY VALIDATION
- 2. CONTROL OF SYSTEMATIC FAULTS (IEC 61508.2-2010- ANNEX A)
 - a) TABLE A.15 TECHNIQUES AND MEASURES TO CONTROL SYSTEMATIC FAILURES CAUSED BY HARDWARE DESIGN
 - b) TABLE A.16 TECHNIQUES AND MEASURES TO CONTROL SYSTEMATIC FAILURES CAUSED BY ENVIRONMENTAL STRESS OR INFLUENCES
 - c) TABLE A.17 TECHNIQUES AND MEASURES TO CONTROL SYSTEMATIC OPERATIONAL FAILURES





Table B.6 (continued)

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Technique/measure	See IEC 61508-7	Low effectiveness	High effectiveness
Dynamic analysis	B.6.5	Based on block diagrams; highlighting weak points; specifying test cases	Based on detailed diagrams; predicting expected behaviour during test cases; using testing tools
Failure analysis	B.6.6	At module level, including boundary data of the peripheral units	At component level, including boundary data
Worst-case analysis	B.6.7	Performed on safety functions; derived using boundary value combinations for real operating conditions	Performed on non-safety functions; derived using boundary value combinations for real operating conditions
Expanded functional testing	B.6.8	Test that all safety functions are maintained in the case of static input states caused by faulty process or operating conditions	Test that all safety functions are maintained in the case of static input states and/or unusual input changes, caused by faulty process or operating conditions (including those that may be very rare)
Worst-case testing	B.6.9	Test that safety functions are maintained for a combination of boundary values found in real operating conditions	Test that non-safety functions are maintained for a combination of the boundary values found in real operating conditions
Fault insertion testing	B.6.10	At subunit level including boundary data or the peripheral units	At component level including boundary data



T;		10	control systematic failures		r influences		
Table A.1	Technique/measure	See IEC 61508-7	Low effectiveness	High effectiveness	SIL 4	ware design	1
Techn	Failure detection by on-line monitoring (see Note)	A.1.1	Trigger signals from the EUC and its control system are used to check the proper operation of the E/E/PE safety-related systems (only time behaviour with an upper time limit)	E/E/PE safety-related systems are retriggered by temporal and logical signals from the EUC and its control system (time window for temporal watch-dog function)	M high	SIL3	SIL4
Table 4	Tests by redundant hardware (see Note)	A.2.1	Additional hardware tests the trigger signals of the E/E/PE safety-related systems (only time behaviour with an upper time limit), this hardware switches a secondary final element	Additional hardware is retriggered by temporal and logical signals of the E/E/PE safety-related systems (time window for temporal watch- dog); voting between multiple channels	tional f	ailures	
Techniqu	Standard test access port and boundary-scan architecture	A.2.3	Testing the used solid-state logic, during the proof test, through defined boundary scan tests	Diagnostic test of solid-state logic, according to the functional specification of the E/E/PE safety- related systems; all functions are checked for all integrated circuits	L 2	SIL 3	SIL 4
Modification protec	Code protection	A.6.2	Failure detection via time redundancy of signal transmission	Failure detection via time and information redundancy of signal transmission	Л	М	М
	Measures against voltage breakdown, voltage variations, overvoltage and low voltage	A.8	Overvoltage protection with safety shut-off or switch-over to secondary power unit	Voltage control (secondary) with safety shut-off or switch-over to secondary power unit; or power-down with safety shut-off or switch-over to secondary power unit	diu n	high	high
Failure detection by	Program sequence monitoring	A.9	Temporal or logical monitoring of the program sequence	Temporal and logical monitoring of the program sequence at very many checking points in the program	R W	R medium	R high
Input acknowledgei	Measures against temperature increase	A.10	Detecting over-temperature	Actuation of the safety shut-off via thermal fuse; or several levels of over-temperature sensing and alarms; or connection of forced-air cooling and status indication	R W	R medium	R high
Failure assertion pro	Increase of interference immunity (see Note)	A.11.3	Noise filter at power supply and critical inputs and outputs; shielding, if necessary	Filter against electromagnetic injection that is normally not expected; shielding	$\frac{2 \text{ and } 0}{R}$	C.2 of IEC 6 ⊣	1508-3
	Measures against physical environment	A.14	Generally accepted practice according to the application	Techniques referred to in standards for a particular application	high R	_	
	Diverse hardware	B.1.4	Two or more items carrying out the same function but being different in design	Two or more items carrying out different functions	high R	_	
	Modification protection	B.4.8	Modification requires specific tools	Modification requires use of key lock or dedicated tool with password	high R high	-	
	Input acknowledgement	B.4.9	Echoing of input actions back to the operator	Checking strict rules for the input of data by the operator, rejecting incorrect inputs	R high	—	
			with references A.1.1, A.2.1, A.11.3 that the low effectiveness approache	3, and A.14 for high effectiveness of	508-3		



IEC 61508.7-2010 B.1.1 Project management

Aim: To avoid failures by adoption of an organizational model and rules and measures for development and testing of safety-related systems.

Description: The most important and best measures are

- The creation of an organizational model, especially for quality assurance which is set down in a quality assurance handbook; and
- The establishment of regulations and measures for the creation and validation of safety related systems in cross-project and project-specific guidelines.

A number of important basic principles are set down in the following:

- Definition of a design organization:
- tasks and responsibilities of the organizational units,
- authority of the quality assurance departments,
- independence of quality assurance (internal inspection) from development;
- Definition of a sequence plan (activity models):
- determination of all activities which are relevant during execution of the project including internal inspections and their scheduling,
- project update;
- Definition of a standardized sequence for an internal inspection:
- planning, execution and checking of the inspection (inspection theory),
- releasing mechanisms for sub-products,
- the safekeeping of repeat inspections;
- Configuration management:
- administration and checking of versions,
- detection of the effects of modifications,
- consistency inspections after modifications;
- Introduction of a quantitative assessment of quality assurance measures:
- requirement acquisition,
- failure statistics;
- Introduction of computer-aided universal methods, tools and training of personnel.



MANAGEMENT OF SOFTWARE INTEGRITY TECHNIQUES AND MEASURES

61508.3-2010 ANNEX A

- TABLE A.1 SOFTWARE SAFETY REQUIREMENTS SPECIFICATION
- TABLE A.2 SOFTWARE ARCHITECTURE DESIGN
- TABLE A.3 SUPPORT TOOLS & PROGRAMMING LANGUAGE
- TABLE A.4 SOFTWARE DETAILED DESIGN
- TABLE A.5 SOFTWARE MODULE TESTING & INTEGRATION
- TABLE A.6 HARDWARE AND SOFTWARE INTEGRATION
- TABLE A.7 SYSTEM SAFETY VALIDATION
- TABLE A.8 MODIFICATION
- TABLE A.9 SOFTWARE VERIFICATION
- TABLE A.10 FUNCTIONAL SAFETY ASSESSMENT



MANAGEMENT OF SOFTWARE INTEGRITY DETAILED TABLES

61508.3-2010 ANNEX B

- TABLE B.1 DESIGN AND CODING STANDARDS
- TABLE B.2 DYNAMIC ANALYSIS AND TESTING
- TABLE B.3 FUNCTIONAL AND BLACK-BOX TESTING
- TABLE B.4 FAILURE ANALYSIS
- TABLE B.5 MODELLING
- TABLE B.6 PERFORMANCE TESTING
- TABLE B.7 SEMI-FORMAL METHODS
- TABLE B.8 STATIC ANALYSIS
- TABLE B.9 MODULAR APPROACH



GUIDE TO THE SELECTION OF TECHNIQUES AND MEASURES

Table A.9 – Software verification

Table A.10 – Functional safety assessment

Assessment/Technique *		Ref.	SIL 1	SIL 2	SIL 3	SIL 4	
1	Checklists	B.2.5	R	R	R	R	
2	Decision/truth tables	C.6.1	R	R	R	R	
3	Failure analysis	Table B.4	R	R	HR	HR	
4	Common cause failure analysis of diverse software (if diverse software is actually used)	C.6.3		R	HR	HR	
5	Reliability block diagram	C.6.4	R	R	R	R	
6	Forward traceability between the requirements of Clause 8 and the plan for software functional safety assessment	C.2.11	R	R	HR	HR	
1	· · · ·						
Programmable electronics integration testing		See Table A.6					
Software system testing (validation)		See Table A.7					
	specification						
Forward traceability between the software safety requirements specification and software design		C.2.11	R	R	HR	HR	

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I Static Synchronisation of access to shared resources

Detailed Tables

 Table B.8 – Static analysis

(Referenced by Table A.9)

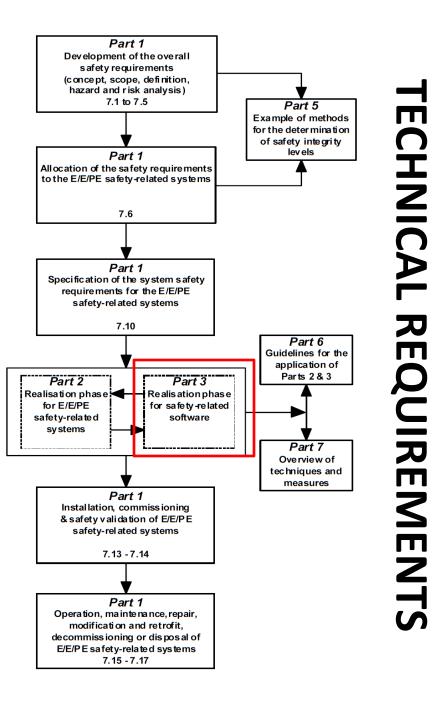
 Table B.9 – Modular approach

(Referenced by Table A.4)

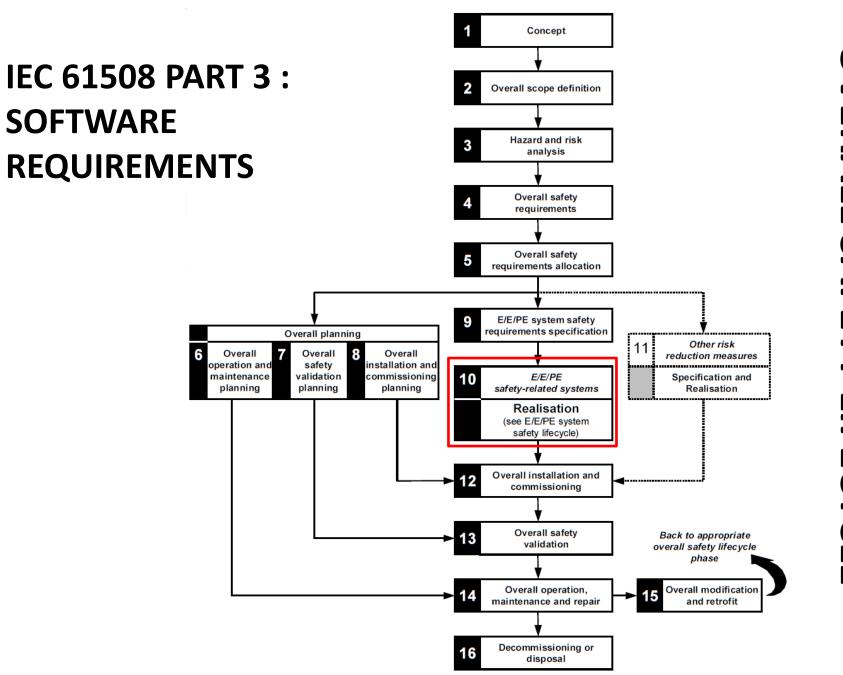
	Technique/Measure *	Ref	SIL 1	SIL 2	SIL 3	SIL 4
1	Software module size limit	C.2.9	HR	HR	HR	HR
2	Software complexity control	C.5.13	R	R	HR	HR
3	Information hiding/encapsulation	C.2.8	R	HR	HR	HR
4	Parameter number limit / fixed number of subprogram parameters	C.2.9	R	R	R	R
5	One entry/one exit point in subroutines and functions		HR	HR	HR	HR
6	Fully defined interface	C.2.9	HR	HR	HR	HR
1	0 Worst-case execution time analysis	C.5.20	R	R	R	R



IEC 61508 PART 3 : SOFTWARE REQUIREMENTS



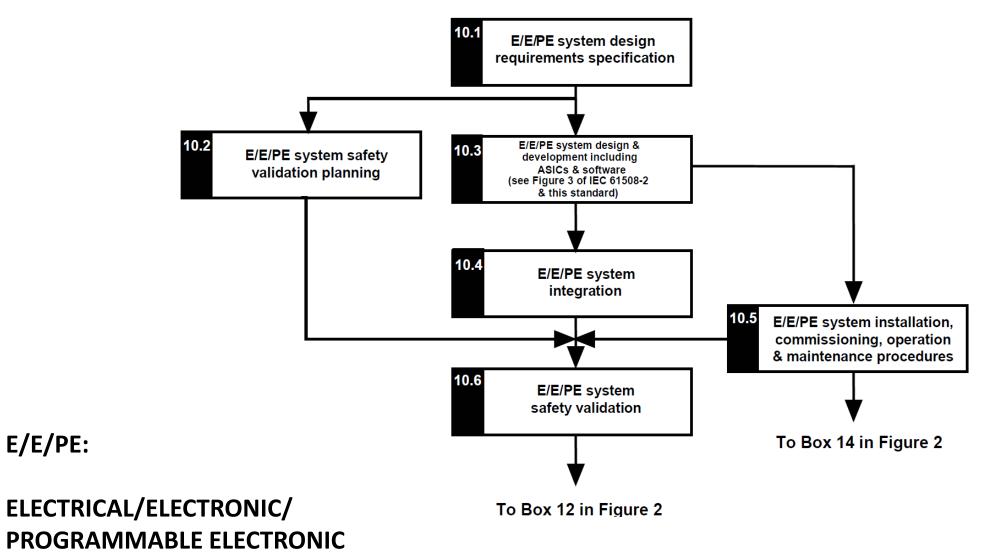








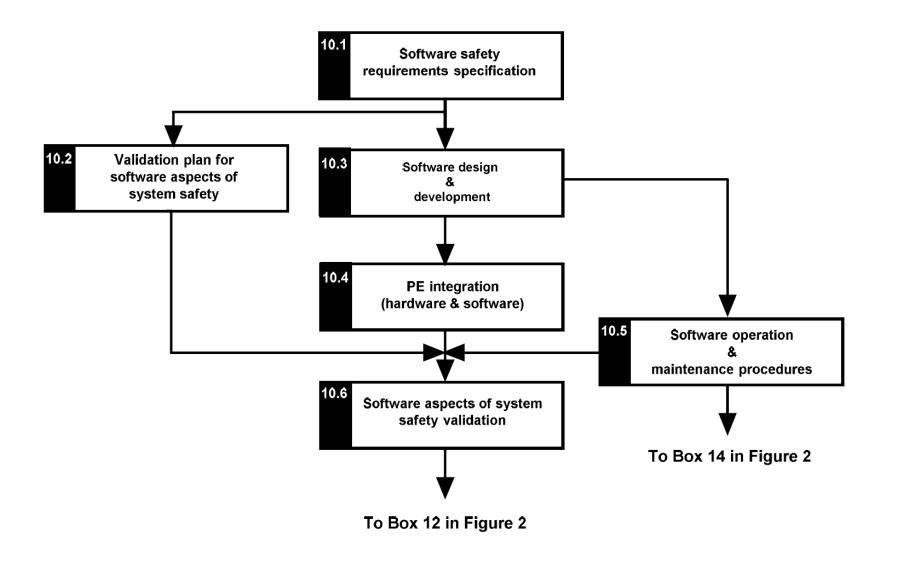
E/E/PE SYSTEM SAFETY LIFECYCLE



E/E/PE:

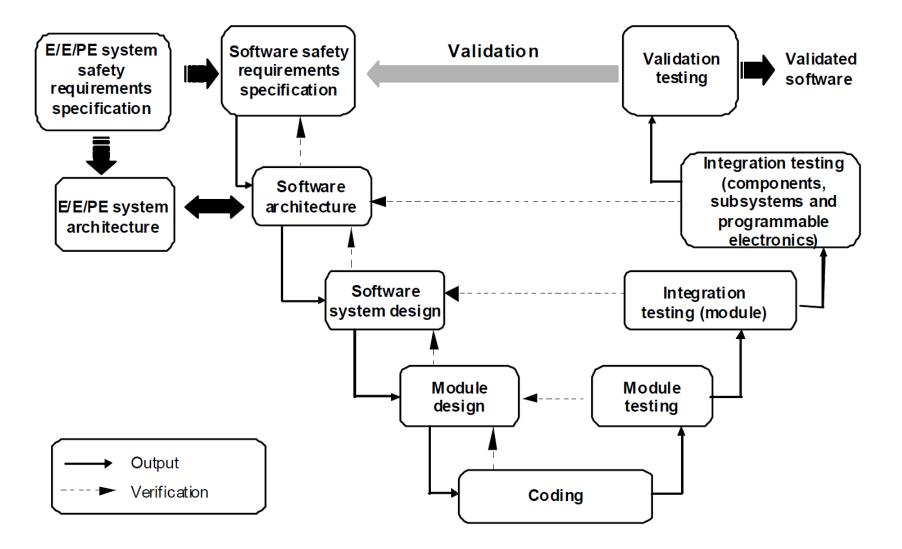


SOFTWARE SAFETY LIFECYCLE





SOFTWARE SYSTEMATIC CAPABILITY AND THE DEVELOPMENT LIFECYCLE (THE V-MODEL)



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AVOIDANCE AND CONTROL OF SYSTEMATIC FAULTS ARE SIGNIFICANTLY MORE DIFFICULT IN COMPARE TO RANDOM FAULTS



SAFETY LIFECYCLE







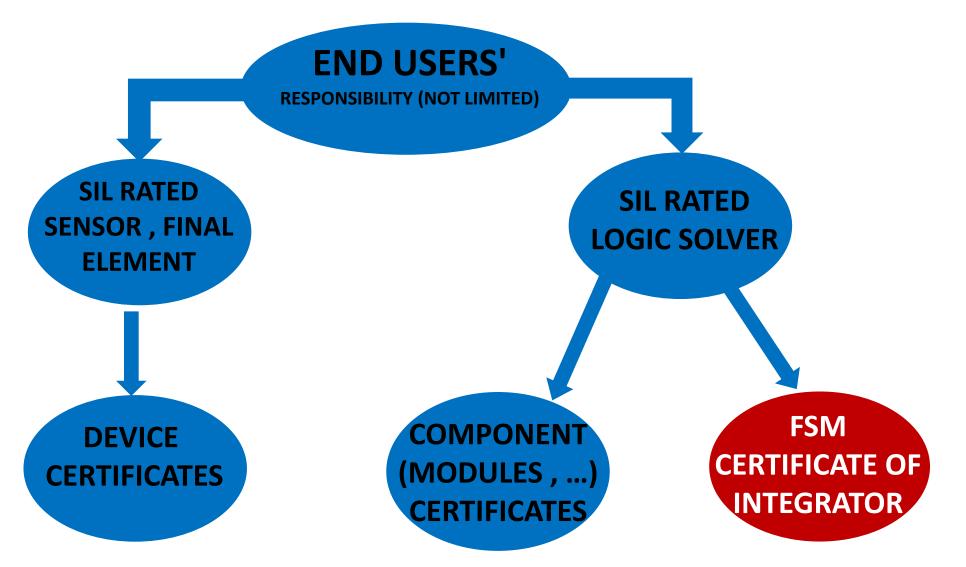
AT DIFFERENT PARTS OF THE SAFETY LIFE CYCLE, DIFFERENT PARTIES ARE RESPONSIBLE FOR THE FSM

OVERALL IS ALWAYS END USER



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EXAMPLE: SELECTION OF SIS ELEMENTS







The manufacturer may use the mark:

CERTIFIE

Surveillance Audit Due

July 1, 2019

ANSI

ANSI Accredited Program PRODUCT CERTIFICATION #1004 Certificate / Certificat Zertifikat / 合格証

exida hereby confirms that the:

Level Transmitter

Has been assessed per the relevant requirements of: IEC 61508 : 2010 Parts 1-7 and meets requirements providing a level of integrity to: Systematic Capability: SC 3 (SIL 3 Capable) Random Capability: Type B Element SIL 2 @ HFT=0; SIL 3 @ HFT = 1; Route 2_H PFD_{AVG} and Architecture Constraints

> Safety Function: The Eclipse 706GWR Level Transmitter will measure level and transmit a corresponding signal within the stated safety accuracy.

must be verified for each application

Application Restrictions:

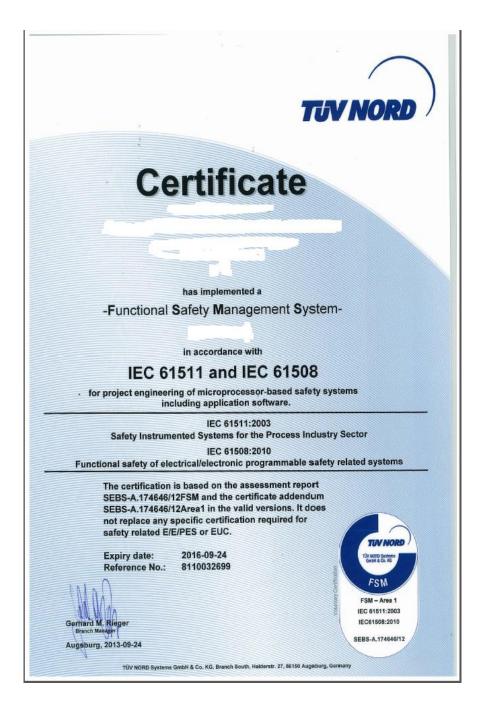
The unit must be properly designed into a Safety Instrumented Function per the Safety Manual requirements.



Certifying Assessor

Page 1 of 2







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QUESTIONS?

